

An Improved Renewable Hybrid Energy based system for Grid connected Applications

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Abstract—A 7.2 KW hybrid system and its control strategy is developed in this paper. this hybrid system is a combination of a photovoltaic generator (PVG) and a fuel cell (FC).PVG is associated with a boost converter with a maximum power point method (MPPT). And FC is connected with a boost converter. To control the power delivered by the systems, an hysteresis control is used. The proposed model is simulated through MATLAB/SIMULINK and their results are presented in this paper.

Keywords- Photovoltaic generator (PVG), Fuel cell (FC), Maximum power point technique (MPPT).

I. INTRODUCTION

The integration of renewable energy sources and energy-storage systems has been one of the new trends in power-electronic technology. The increasing number of renewable energy sources and distributed generators requires new strategies for their operations in order to maintain or improve the power-supply stability and quality. Combining multiple renewable resources via a common dc bus of a power converter has been prevalent because of convenience in integrated monitoring and control and consistency in the structure of controllers as compared with a common ac type.

Solar energy is one of the most important renewable energy sources. As opposed to conventional non-renewable resources such as gasoline, coal, etc., solar energy is clean, inexhaustible and free. Unfortunately, PV generation systems have two major problems: the conversion efficiency of electric power generation is very low (9-17%), especially under low irradiation conditions and the amount of electric power generated by solar arrays changes continuously with weather conditions.

Moreover, the solar cell V-I characteristic is nonlinear and varies with irradiation and temperature. In general, there is a unique point on the V-I or V-P curve, called the Maximum Power Point (MPP), at which the entire PV system (array, converter, etc.) operates with maximum efficiency and produces its maximum output power. The location of the MPP is not known, but can be located, either through calculation models or by search algorithms. Therefore Maximum Power Point Tracking (MPPT) techniques are needed to maintain the PV array's operating point at its MPP.

Fuel cell is an electrochemical device that converts oxygen and hydrogen to electrical power with water as the only by product. Fuel cell based power systems are considered as one of the most promising and clean energy sources. Fuel cell systems are truly heterogeneous systems involving mechanical, chemical, thermal and electrical systems. This makes system level modelling a significant challenge that very few modelling tools can handle. The challenges consist of both numerical issues and model configuration management issues. In this paper the modelling of this fuel cell is also done.

Both the photovoltaic and fuel cell models are integrated in a hybrid system. The control of this grid

connected hybrid system is discussed and their simulation results are presented in this paper.

II. SYSTEM CONFIGURATION

The fig.1 shows the configuration of the proposed hybrid system. This hybrid system consists of a PV generator and a Fuel cell. The PV generator system consists of a PV array modelling and a boost converter to boost the voltage to a higher level. And also an MPPT method is used to track maximum power. The fuel cell also consists of its modelling and a boost converter. Both these systems are connected in parallel and are connected to an inverter. The inverter is controlled based on the hysteresis control to the inverter other end a transformer is connected. And to the transformer grid and local loads are connected.

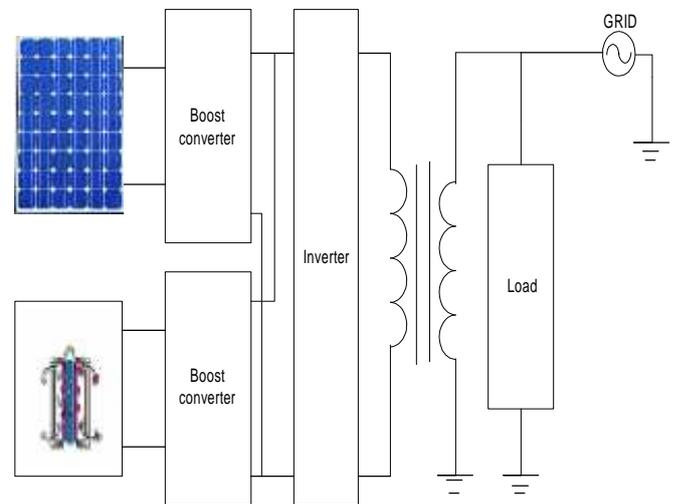


Fig.1 configuration of hybrid system

III. PV MODELING

A PV generator is assembly of solar cells, connections, protective parts, supports etc. In the present modelling, the focus is only on cell/module/array. A p-n junction diode fabricated in a thin wafer or layer of semiconductor generally silicon is present inside the solar cell. In the dark, the output characteristic of a solar cell (I-V characteristics) has an

- Shunt resistance R_{sh} , in parallel with the diode, this corresponds to the leakage current to the ground and it is commonly neglected.
- Either allowing the diode quality factor n to become a variable parameter (instead of being fixed at either 1 or 2) or introducing two parallel diodes with independently set saturation currents. In an ideal cell $R_s = R_{sh} = 0$, which is a relatively common assumption. For this paper, a model of moderate complexity was used. The net current of the cell is the difference of the photocurrent, I_L and the normal diode current I_0 .

- Short circuit current: $I_{sc} = I_{ph}$. It is the greatest value of the current generated by a cell. It is produced by the short circuit conditions: $V = 0$.
- Open circuit voltage corresponds to the voltage drop across the diode (p-n junction), when it is transverse by the photocurrent I_{ph} (namely $I_L = I_{ph}$), namely when the generated current is $I = 0$. It reflects the voltage of the cell in the night and it can be mathematically expressed as:

Where V_t is known as thermal voltage and T is the absolute cell temperature.

- Maximum power point is the operating point $A(V_{max}, I_{max})$ at which the power dissipated in the resistive load is maximum:

$$P_{max} = V_{max} * I_{max}$$

- Maximum efficiency is the ratio between the maximum power and the incident light power.

Where G_a is the ambient irradiation and A is the Cell area.

IV. FUEL CELL

The FC system converts the hydrogen into electrical energy. The core of the FC consists of two electrodes, the anode and the cathode, separated by a membrane electrolyte. The most common way to characterise the performances of the FC is the static polarisation curve. The main parameters which affect the FC performances are the membrane and electrode characteristics, the cell design, the operating pressure, temperature and purity of the gases. Figure 4 shows such a polarisation curve (voltage of the cell versus current density). The shape is due to four major irreversibilities: activation losses, fuel crossover and internal currents, ohmic losses in the electrodes and in the membrane, mass transport or concentration losses.

The polarisation curve shown in fig.3 is computed, and it is known as Tafel equation:

This equation takes into account the temperatures, the pressures of oxygen and hydrogen as well as the current going through the FC.

E_o is the cell EMF at standard pressure.

This is known as the Nernst voltage and is the reversible cell voltage that would exist at given temperature and pressure.

The overvoltage $b \cdot \ln(i)$ takes into account the activation losses due to the slowness of the reactions taking place on the surface of the electrodes.

The voltage drop $R \cdot i$ is due to the resistance of the assembly electrodes - membrane - bipolar plates.

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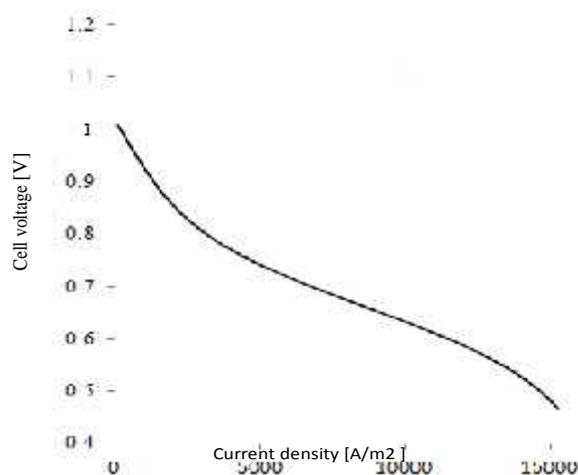


Fig.3.Example of polarisation curve

The voltage of a single cell is quite small. This means that to produce enough voltage, several cells have to be connected in series to create a stack. Furthermore the FC stack cannot operate alone: air and fuel will need to be circulated through the stack using pumps, fans, a compressor, etc. These devices are known as auxiliaries or parasitics. Their power consumption has to be taken into account in the calculation of the FC system efficiency. The auxiliaries can be connected to the DC bus or to the grid. We will only consider the second case in this paper. The simulation of the FC system as well as the simulations of the other power supply subsystems is made in the MATLAB/SIMULINK environment.

The maximal power of the FC stack is 330kW. Its voltage output varies between 600V (no load) and 300V.

Boost converters:

A DC-DC boost converter is used to realise the voltage adaptation between the FC output E and the DC bus V_o . The equations of the topologic model are the following ones:

Where $u=0$ or $u=1$

A DC bus voltage V_o of 1500V is chosen in order to allow an ideal control of the current references. The following equation must be checked:

V_{grid} is the RMS grid voltage (230 V), I_{grid} is the maximal grid current, ω is the frequency (rad/s), R_{in} and L_{in} are respectively the phase resistance and phase inductance ($L_{in} = 10$ mH, $R_{in} = 0.1$ n).

V. CONTROL STRATEGY

Here there are two types of controls type1 and type0 it is users decision on which control he wants to use here ppv is the calculated amount of power generated by the PVG, $pload$ is the amount of power required by the load pfc is the power generated by the fuel cell, $ppvmin$ and $pfcmax$ are the threshold minimum and maximum power limits of PVG and fuel cell respectively.

```

if (Type==1)
    if (Ppv > Pload)
        Ppvref = Ppv;
        Pfcref = 0;
        FConoff = 0;
    elseif ((Ppv > Ppvmin) && (Ppv <=
Pload)) %Both PV and FC %
        Ppvref = Ppv;
        FConoff = 1;
        Pfc = Pload-Ppv;
        if (Pfc < Pfcmax)
            Pfcref = Pfc;
        else
            Pfcref = Pfcmax;
        end
    elseif ((Ppv <= Ppvmin) && (Pload >
Pfcmin)) % Only FC%
        Ppvref = 0;
        FConoff = 1;
        if (Pload <= Pfcmax)
            Pfcref = Pload;
        else
            Pfcref = Pfcmax;
        end
    elseif ((Ppv <= Ppvmin) && (Pload <
Pfcmin)) %FC at minimum power%
        Ppvref = 0;
        FConoff = 1;

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Pfcref = Pfcmin;
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end
elseif (Type==0)
    FConoff = 1;
    if ((Ppv < Pload) && (Ppv > Ppvmin))
        Ppvref = Ppv;
        Pfcref = Pload-Ppv;
    end
end
end

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VI. RESULTS

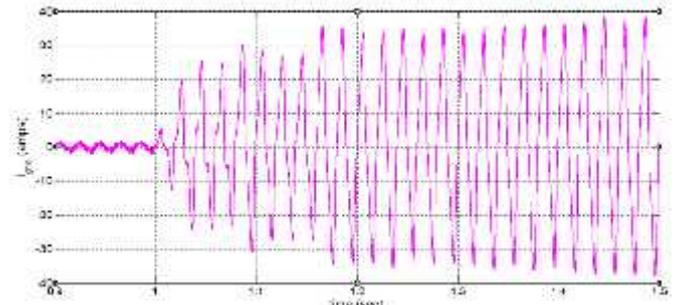


Fig.5 grid current

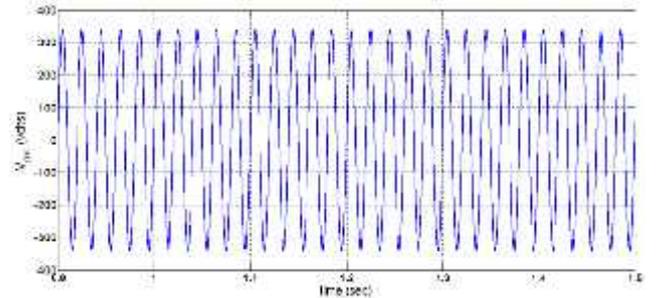


Fig.6 grid voltage

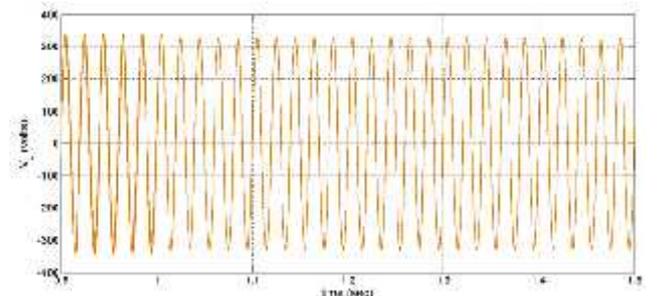


Fig.7 load voltage

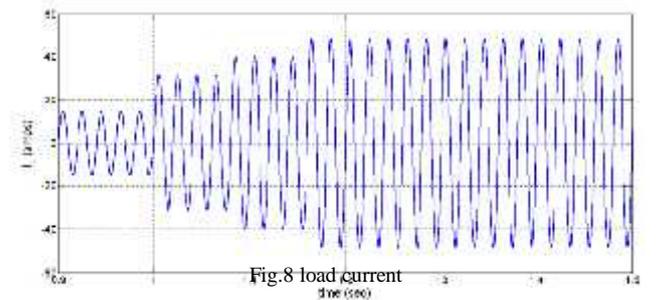


Fig.8 load current

VII. CONCLUSION

In this paper power control strategy for versatile power transfer for a grid-connected PV/FC hybrid system has been proposed. Two modes of operations were added for flexible operation and improvement in quality of power delivered to the grid. A hysteresis control was applied to control the power delivered to the local load and the grid. The proposed control offers grid or user a friendly option in operating modes. Simulation results provided various dynamic characteristics of the proposed control scheme, which enabled comprehensive quantitative and qualitative analysis before a real hardware implementation.

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